# Adaptively Tracking the Best Arm with an Unknown Number of Distribution Changes



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#### Introduction

Problem setting

- Multi-Armed Bandits (MAB): Simple setting for explorationexploitation trade-off.
- Classical stochastic MAB: Stationary reward distributions.
- → Switching Bandits [1]: Stochastic MAB with non-stationary reward distributions .
- ▶ Application : Real-time content optimization of websites.

#### Regret Bound

**Theorem 1.** When ADSWITCH is run with with sufficiently large  $C_1$  and  $C_2$ , then its regret for a switching bandit problem with two arms and L changes is at most

 $O((\log T)\sqrt{(L+1)T}).$ 

#### Discussion and Further Directions

- The best known lower bound is  $\Omega(\sqrt{LT})$ , which holds even when L is given to the algorithm.
- Previously, upper bounds  $\tilde{O}(\sqrt{LT})$  were known only for algorithms
- At each time t = 1, 2, ..., T, algorithm  $\mathfrak{A}$  selects an arm  $a_t \in \{1, 2\}$ .
- It receives  $r_t \sim D_t(a_t)$  with mean  $\mu_t(a_t)$ .
- Reward distributions  $D_t$  may change abruptly at certain times.
- Algorithm has no knowledge about the number of changes L.

• Optimize regret  $\mathbf{R}_{\mathfrak{A}} = \sum_{\mathbf{t}=1}^{\mathbf{T}} \max_{\mathbf{a}} \mu_{\mathbf{t}}(\mathbf{a}) - \mathbb{E}\left[\sum_{\mathbf{t}=1}^{\mathbf{T}} \mu_{\mathbf{t}}(\mathbf{a}_{\mathbf{t}})\right].$ 

## Algorithm ADSWITCH (Sketch)

- **Episodic algorithm** with each episode having two phases.
- Estimation phase: Both arms are selected alternatingly, until better arm has been identified.
- Exploitation and checking phase:
  - $\triangleright$  Mostly exploit the empirical best arm.
  - Sometimes sample both arms to check for change.If a change is detected then a new episode is started.

- which receive L as input [1, 2].
- Our algorithm can be extended for K arms and achieves  $O\left(K(\log T)\sqrt{(L+1)T}\right)$  regret.
- A version of our algorithm achieves variational regret  $\tilde{O}\left(V^{1/3}T^{2/3}\right)$ (which is order-optimal [3]) without knowing the variation  $V = \sum_t \max_a |\mu_t(a) - \mu_{t-1}(a)|.$
- Future work: Switching adversarial bandits and Markov Decision Processes.

#### Key references

- [1] Aurélien Garivier and Eric Moulines: On upper-confidence bound policies for switching bandit problems, ALT 2011.
- [2] Robin Allesiardo, Raphael Féraud and Odalric-Ambrym Maillard: The non-stationary stochastic multi-armed bandit problem, IJDSA 2017.
- [3] Omar Besbes, Yonatan Gur, and Assaf Zeevi: Stochastic Multi-Armed-Bandit Problem with Non-stationary Rewards, NIPS 2014.

### Algorithm $\operatorname{AdSWITCH}$

- 1: Input: Time horizon T
- 2: **Parameters:**  $C_1, C_2 > 0$
- 3: Initialize k = 0
  - For each episode k, let  $\tau_k^0$  be the time when episode k starts.

Estimation of  $\hat{\Delta}_k$ :

4: Sample both arms alternatingly until the condition of Step 5 is met. Let μ̂<sub>a</sub>[t<sub>1</sub>, t<sub>2</sub>] be the empirical mean for arm a for samples obtained from times t ∈ [t<sub>1</sub>, t<sub>2</sub>).
5: If at time t there is a σ, τ<sup>0</sup><sub>k</sub> ≤ σ < t, with</li>

$$\left|\hat{\mu}_1[\sigma, t] - \hat{\mu}_2[\sigma, t]\right| > \sqrt{\frac{C_1 \log T}{t - \sigma}}$$

then set

$$\hat{\mu}_{k,a} = \hat{\mu}_a[\sigma, t] \quad \text{and} \quad \hat{\Delta}_k = |\hat{\mu}_{k,1} - \hat{\mu}_{k,2}|,$$
$$\bar{a}_k = \arg\max_a \hat{\mu}_{k,a} \quad \text{and} \quad \underline{a}_k = \arg\min_a \hat{\mu}_{k,a}$$

and proceed with Step 6.

Exploitation and checking:

6: Let  $d_i = 2^{-i}$  and  $I_k = \max\{i : d_i \ge \hat{\Delta}_k\}$ . Randomly choose i from  $\{1, 2, \dots, I_k\}$  with probabilities  $\mathbf{p}_{\mathbf{k}, \mathbf{i}} = \mathbf{d}_{\mathbf{i}} \sqrt{\frac{\mathbf{k}+\mathbf{1}}{\mathbf{T}}}$ . With the remaining probability select arm  $\bar{a}_k$  and repeat step 6. If an i is chosen, sample both arms alternatingly for  $\mathbf{s}_{\mathbf{i}} = \mathbf{2} \begin{bmatrix} \mathbf{C}_2 \log \mathbf{T} \\ \mathbf{d}_{\mathbf{i}}^2 \end{bmatrix}$  steps to check for changes of size  $d_i$ : if for any arm a,

$$\hat{\mu}_{\bar{a}_k}[t,t+s_i] - \hat{\mu}_{\underline{a}_k}[t,t+s_i] \notin \left[\hat{\Delta}_k - \frac{d_i}{4}, \hat{\Delta}_k + \frac{d_i}{4}\right],$$

then set  $k \leftarrow k + 1$ , and start a new episode at Step 4.